

Sensors for Crop Productivity, Yield Maps

Area 2 – Technologies
Lesson 4 – Proximal Sensing
Sequence ID – 13

UPM



About the Teacher



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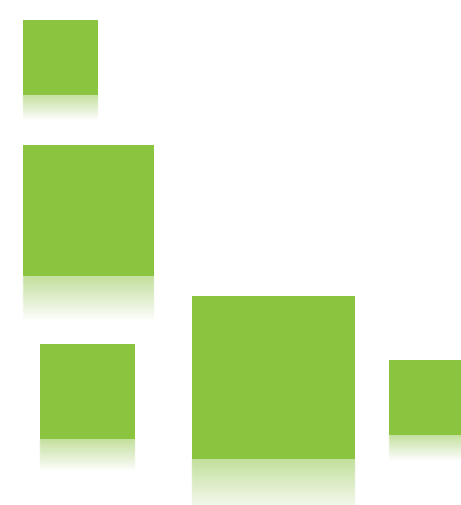
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DISCLAIMER

A2.L4.T1 Sensors for crop productivity, yield maps

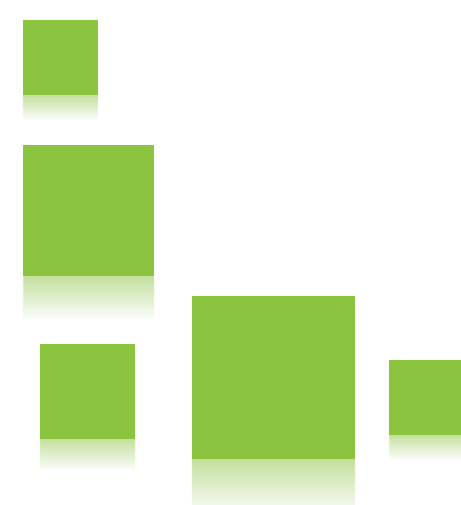
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Interest of Estimating Crop Yield

kg/ha

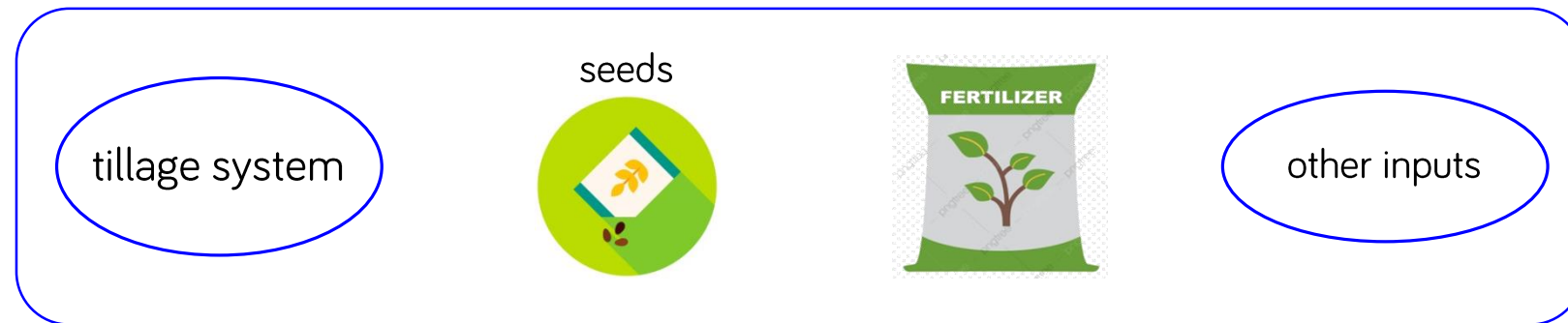
- **Plant Breeder/variety owner**

Assess Yield of **new varieties/cultivars**



- **Farmer**

Measure the effect of different soil conditions or **crop growing practices** on crop Yield



- **National agricultural authority**

Gather data of crop Yields all over the country



(**statistics**, agricultural policy)

Level of complexity in grain yield measuring: *Basic*



(on-the-ground weighbridge)



urbinavinos.com

(picture is of a wine-making facility, i.e. grapes)



medium.com

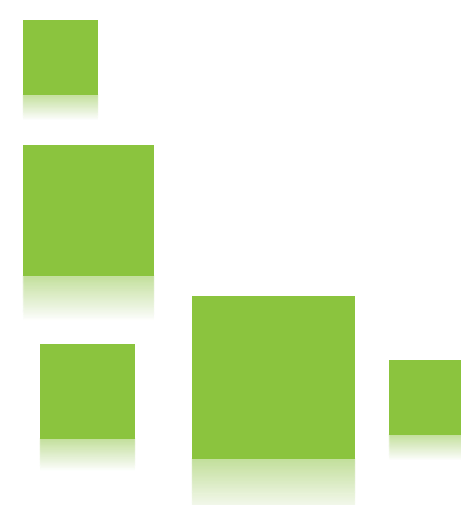
(ground-flush weighbridge)

Weighbridge
(a.k.a. truck scale)

Drawbacks:

Just one single average yield value for the whole field/plot

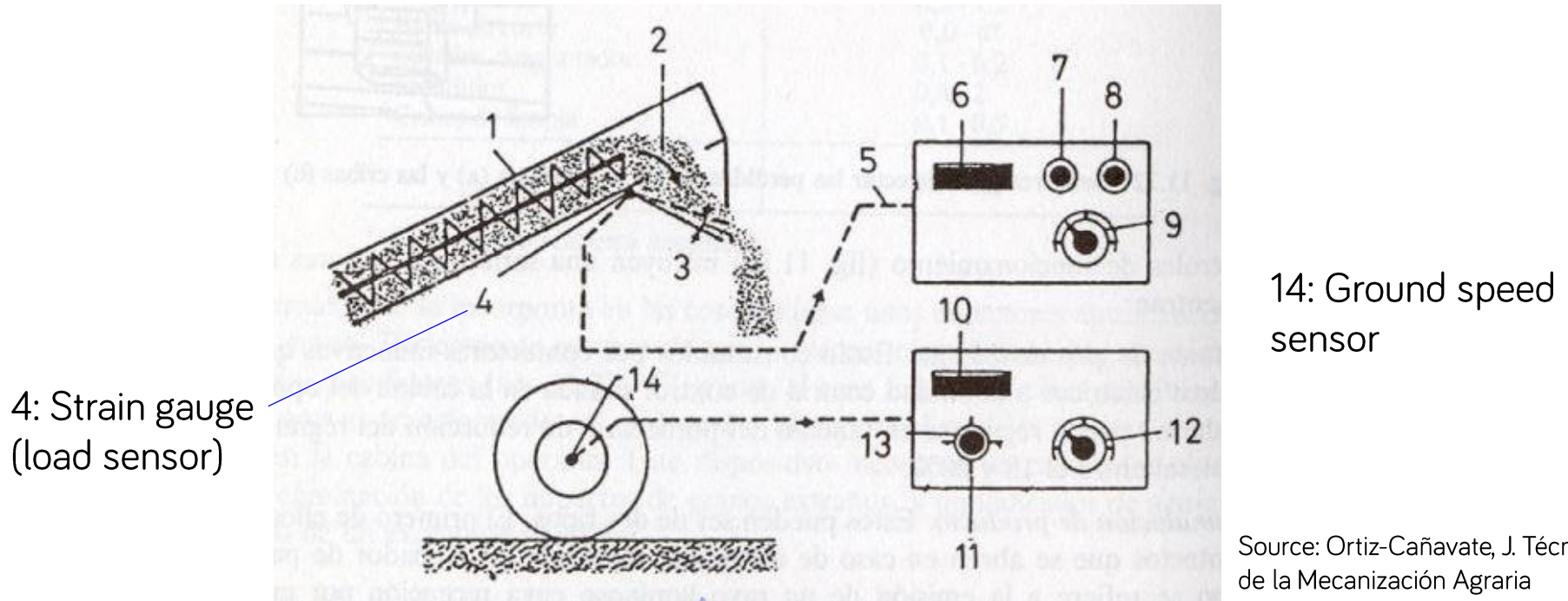
Typically, the last trailer (Eur./Spain) loaded with the plot grain will be only partially full



Level of complexity in grain yield measuring: *Intermediate*



Continuous weighing (kg/s) & m² harvested/s → kg/ha



Source: Ortiz-Cañavate, J. Técnica de la Mecanización Agraria

- Every time the combine hopper is dumped, the cumulated kg up until then is recorded
- Advantage over weighbridge method: plot yield measuring is on-the-go → multiple values of kg/ha
- Shortcoming: no GNSS ⇒ no yield map

Level of complexity in grain yield measuring:

Advanced

HW components for Yield Mapping (Geo-referenced)



Impact Force Sensor

Differential GNSS receiver

Yield monitor (user interface)

Mass flow Yield sensor

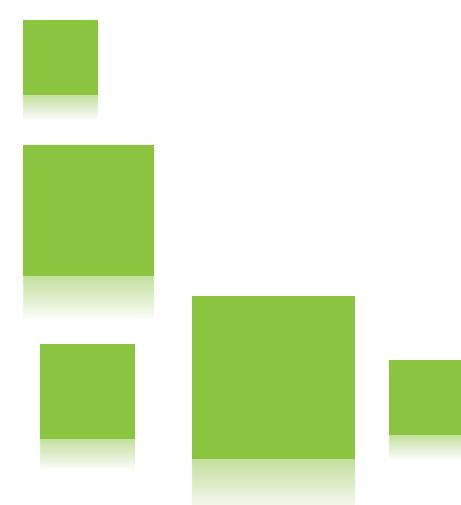
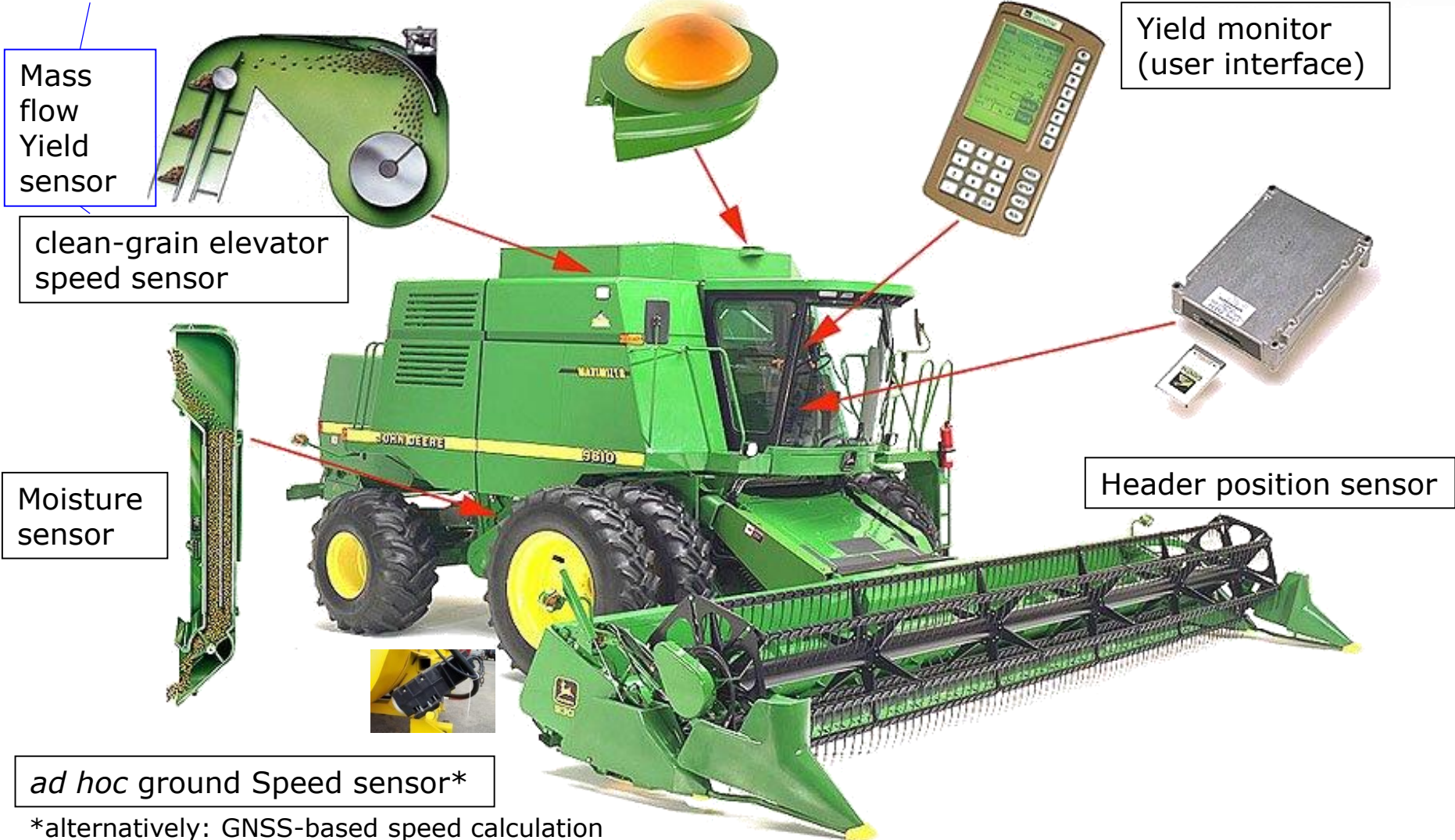
clean-grain elevator speed sensor

Moisture sensor

Header position sensor

ad hoc ground Speed sensor*

*alternatively: GNSS-based speed calculation



Combine Harvester Yield Monitor (1/2)

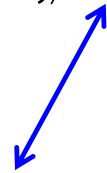


Mass Flow (t/h), wet \Rightarrow “raw” or uncorrected value



Combine Harvester Yield Monitor (2/2)

average Yield
(bu/ac), 'dry'



reference or
desired moisture
content (MC)



Colin W. Wrigley:

A bushel is primarily an American measure of volume, but it has also become a measure of mass (weight); however, its weight differs for each of several grain species

1 bu (wheat) = 60 lb

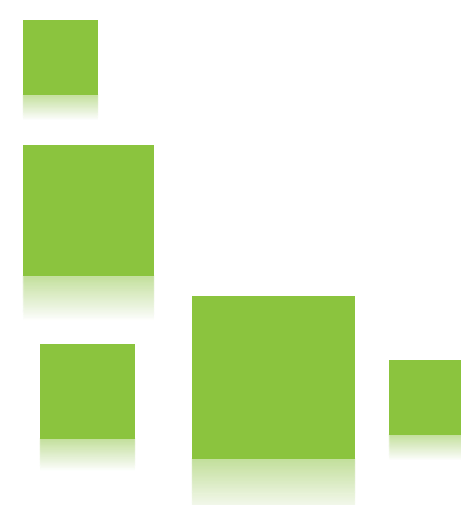
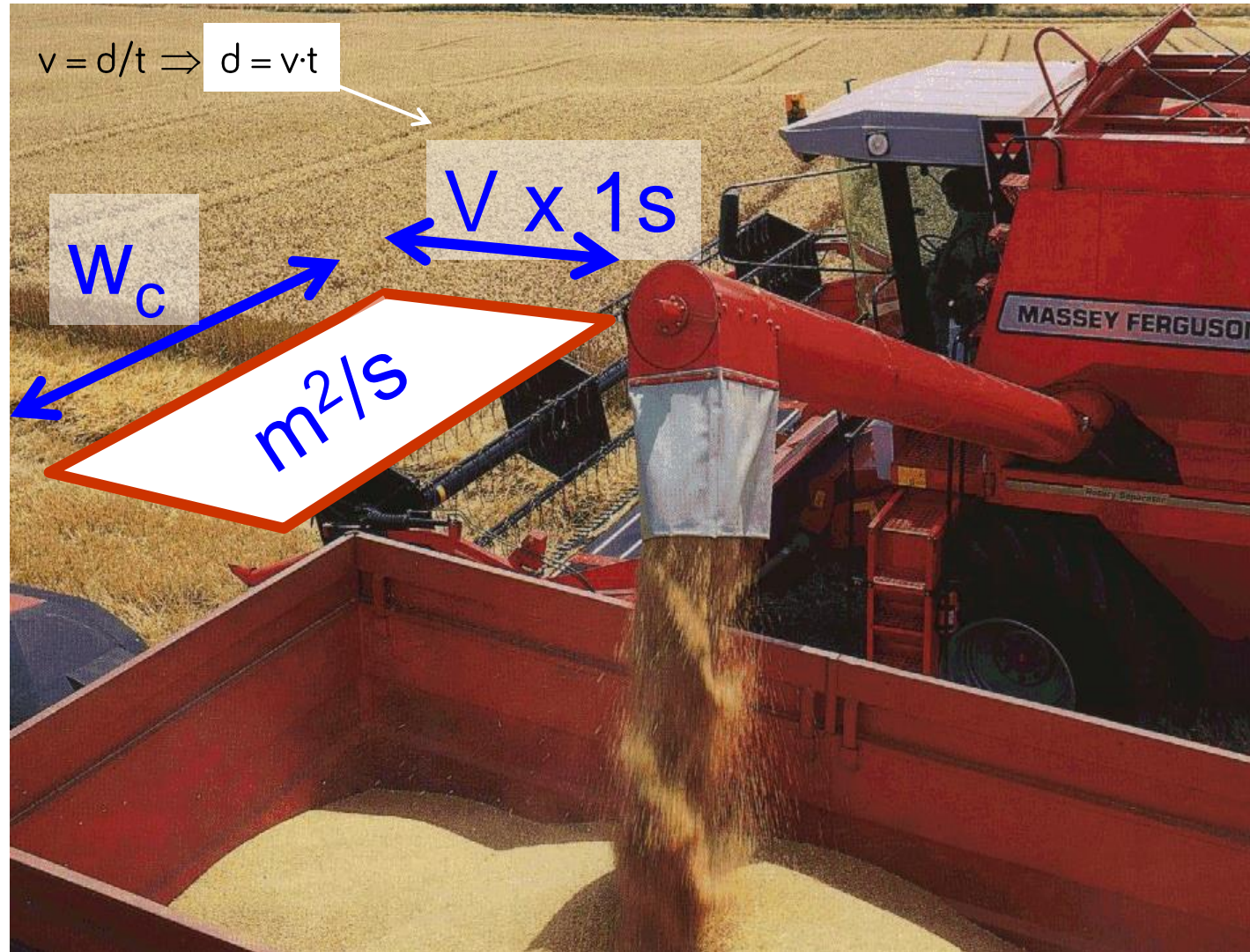
1 bu (corn) = 56 lb

1 ac = 0.4047 ha

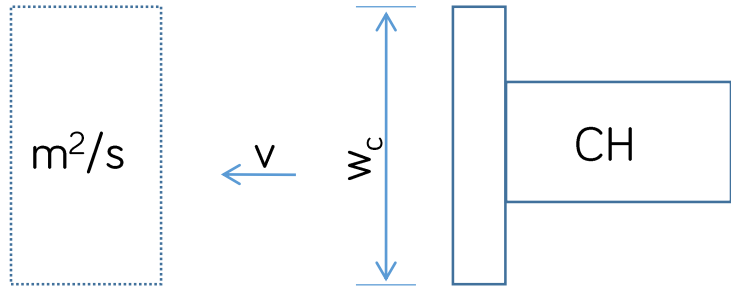
Wheat, rule of thumb: lb/ac $\xrightarrow{\times 1.1}$ kg/ha \longrightarrow

Wrigley, C.W. (2010). Equivalence between metric and U.S. units for the grain industry. *Cereal Foods World*, 55(1): 32-34

Yield Computation (1/3)



Yield Computation (2/3)



$$\text{Yield (wet)} = \frac{\text{kg/s}}{\text{m}^2/\text{s}} = \frac{\text{kg}}{\text{m}^2}$$

(grain with its actual-field- $\text{MC}_{\text{harvest}}$)

lag-time or delay: 5-20 s: **average time** elapsed between the instant when a crop plant is mown and the instant when its grains impact against the mass flow sensor. This lag is taken into account for **yield map** construction.

Yield Computation (3/3)

Moisture Content (MC) correction

- Moisture Sensor (**MS**): only a fraction (sample) of the grain flow is presented to this sensor
- Complemented with a temperature sensor

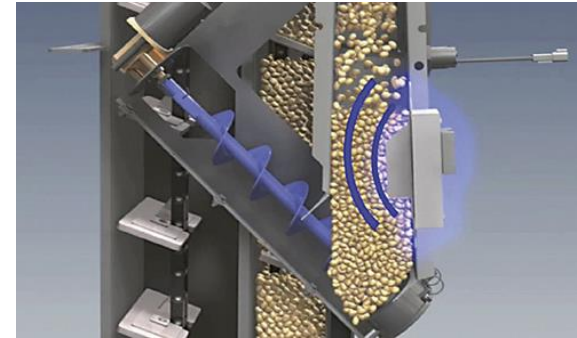
$$Y \text{ ('dry')} = Y \text{ (wet)} \cdot \frac{100 - MC_{\text{harvest}}}{100 - MC_{\text{reference}}}$$

Example: $MC_{\text{harvest}} = 18\%$

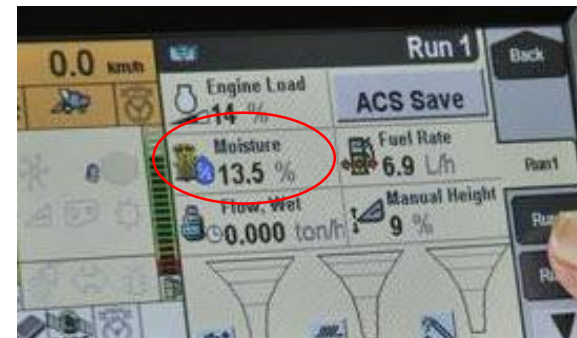
$MC_{\text{ref.}} = 13\%$

$$\frac{100 - MC_{\text{harvest}} = 82}{100 - MC_{\text{ref.}} = 87} = \frac{82}{87} \approx 0.94 (< 1)$$

- Apart from yield mapping, **MS** readings are valuable for CH optimum adjustment (thresher concave-cylinder clearance)



New Holland's MS measures **grain moisture** in real time. Samples are taken every 30 s and the data is sent to the monitor



MS requires periodic calibration (e.g. against accurate hand-held grain MS)

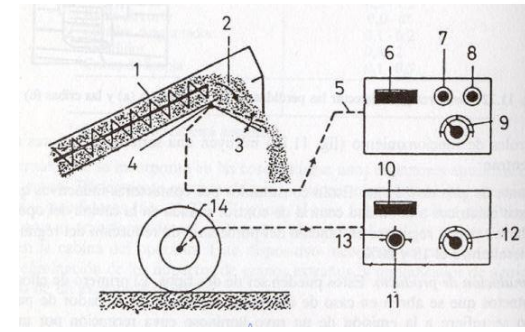
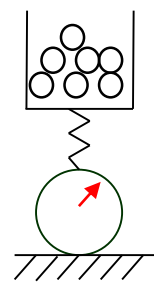
- If the **MS** overestimates grain MC, **Y** will be underestimated

Example (continued): Let the MS reading be 20% (while true or actual is 18%):
 $100 - MC_{\text{harvest}} = 80$; $80/87 = 0.92 (< 0.94)$

Types of yield sensors

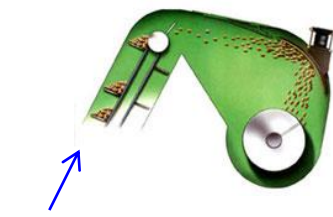
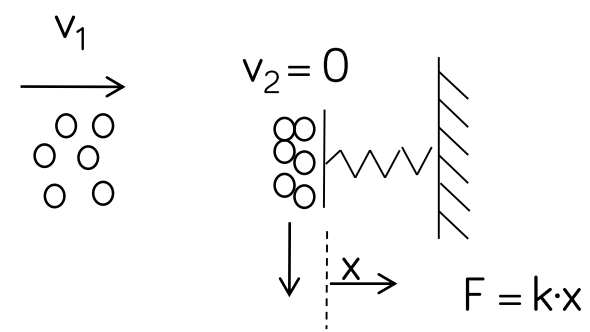
Mass Flow

- Gravimetric (m·g)



→ kg/s

- Momentum (m·v) variation
(a.k.a. impact force yield sensor)

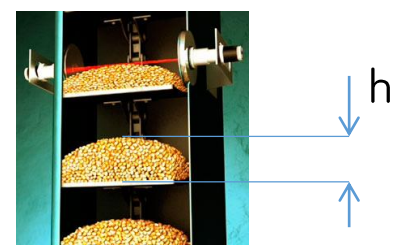


Clean-grain elevator

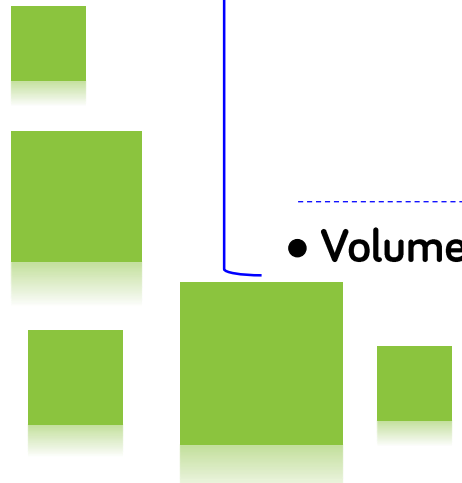
→ kg/s

- Volumetric (from h)

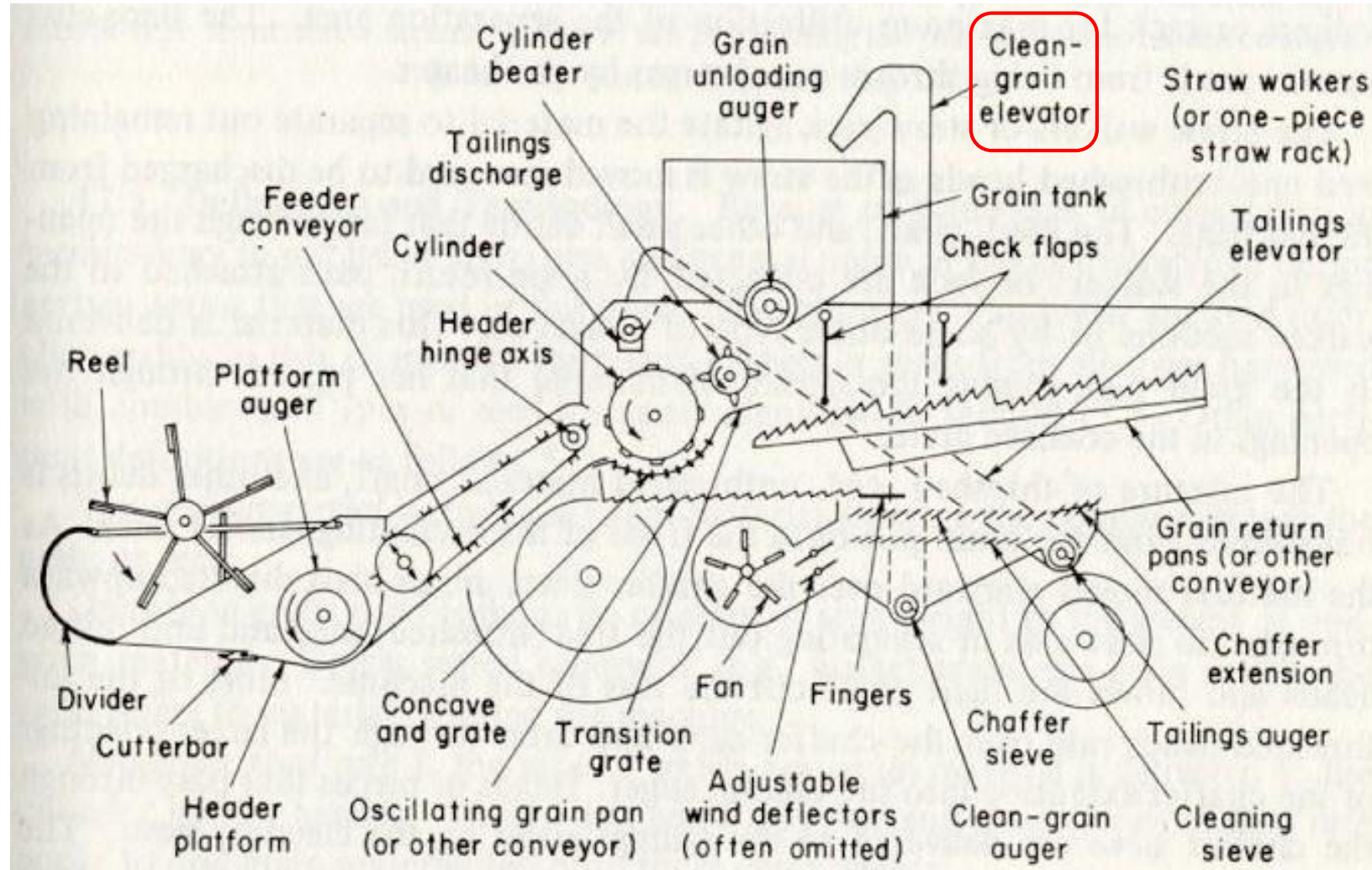
$$V = a \cdot b \cdot h$$



→ L/s



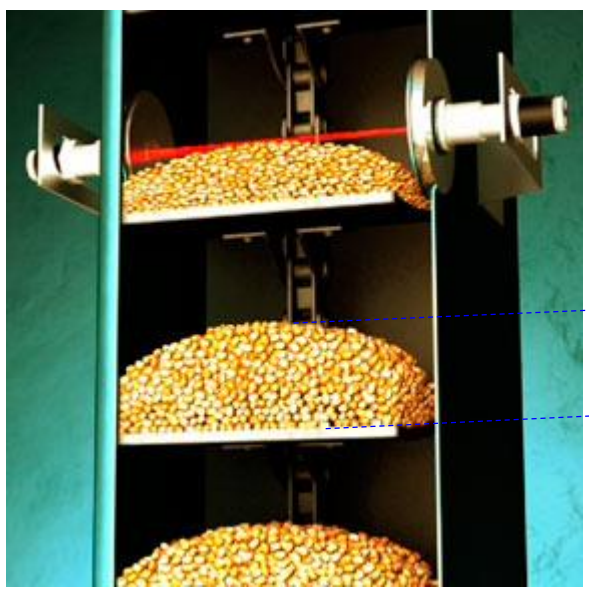
Location of the *clean-grain elevator* in the CH



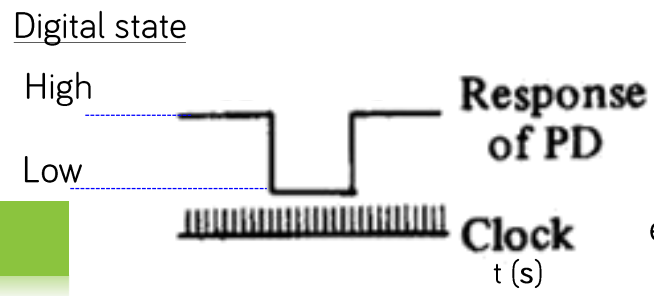
Volumetric yield sensor (1/3)

Optical

clean-grain elevator

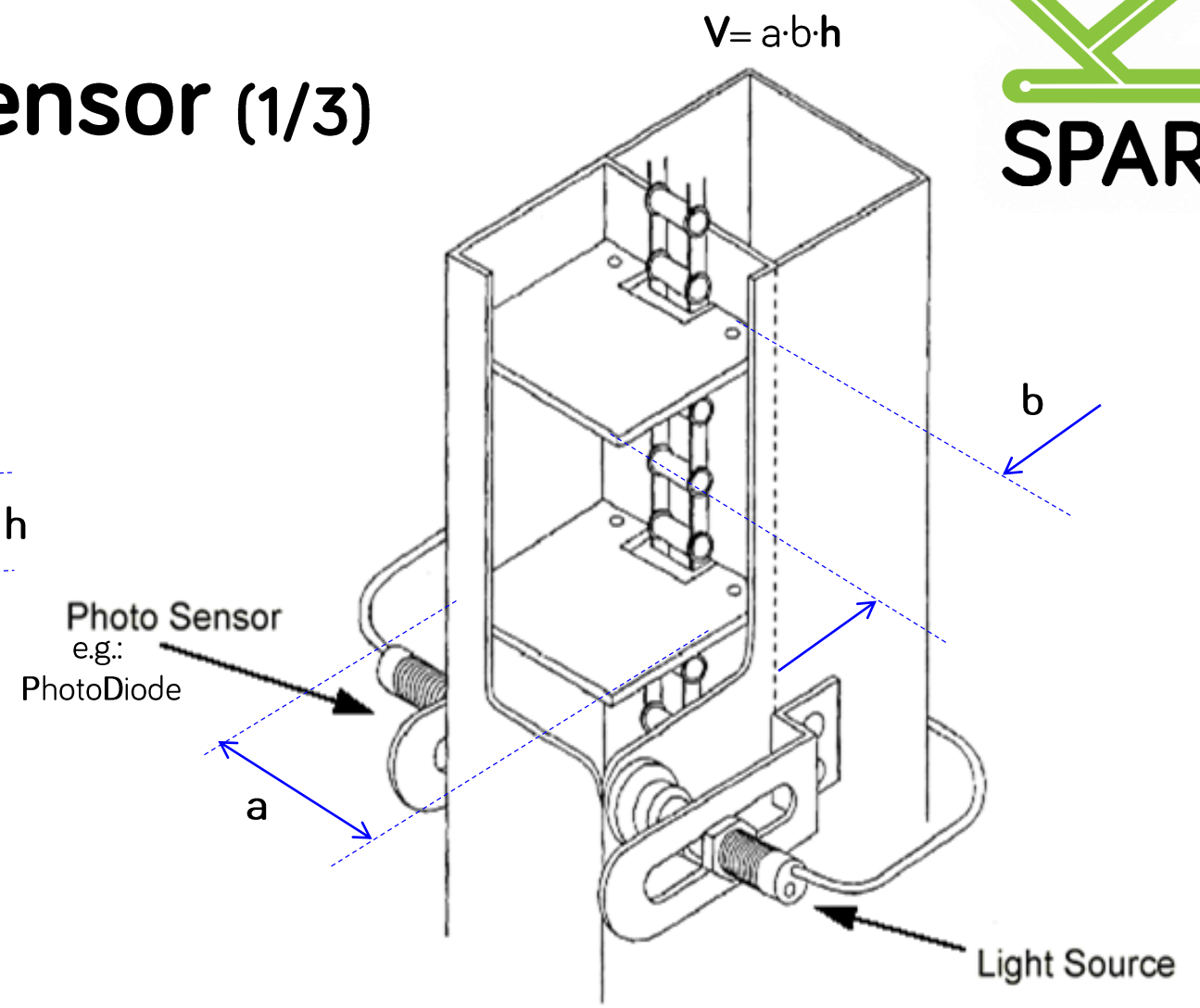


$\uparrow h \Rightarrow \uparrow t_{\text{light blocked}}$



e.g.:

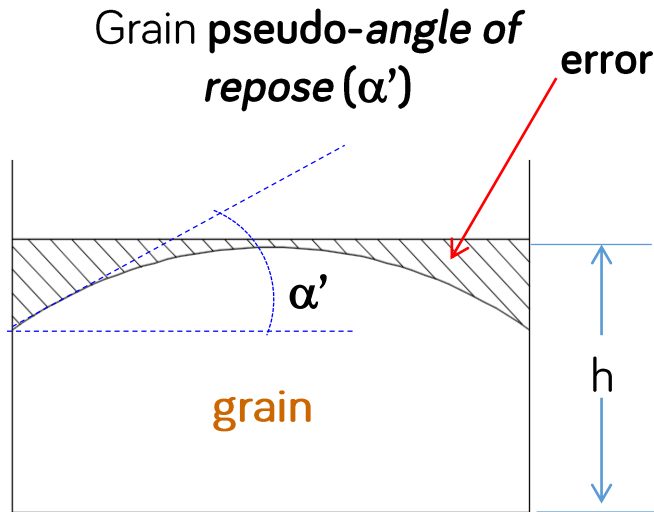
- High \rightarrow Light detected
- Low \rightarrow Light blocked (grain)



Result: **L/s** (finally converted to kg/s by means of estimating a *test weight* (apparent specific weight))

Volumetric yield sensor (2/3)

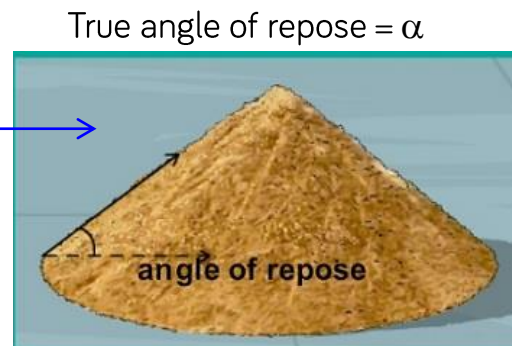
Optical, Sources of Error



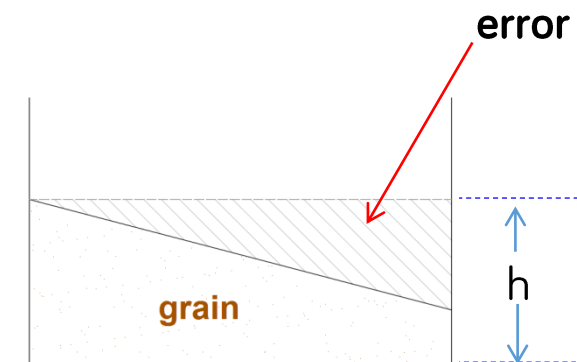
$$V \neq a \cdot b \cdot h$$

(α' can be *a priori* estimated)

'pseudo' is to differentiate the 'bucket' elevator case -constraining lateral walls- from:

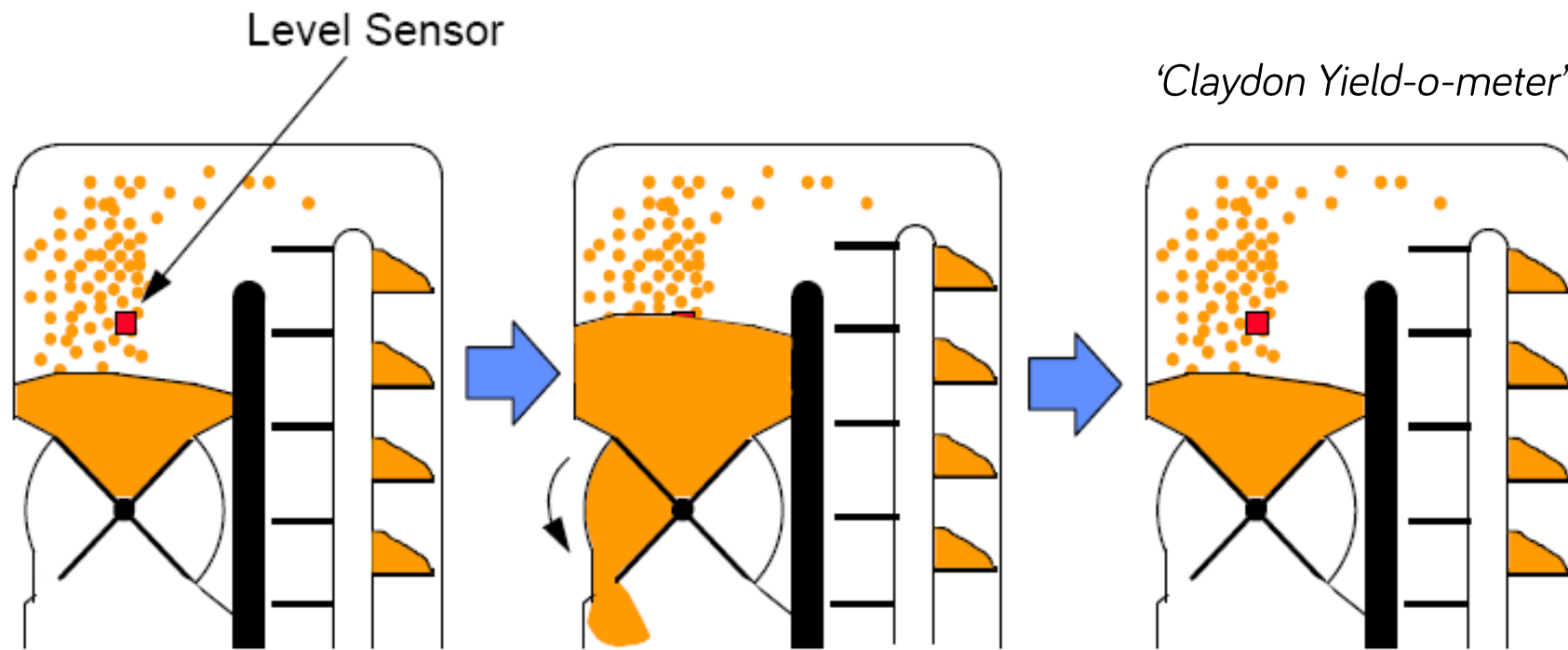


Combine harvester inclination due to **terrain slope**



Volumetric yield sensor (3/3)

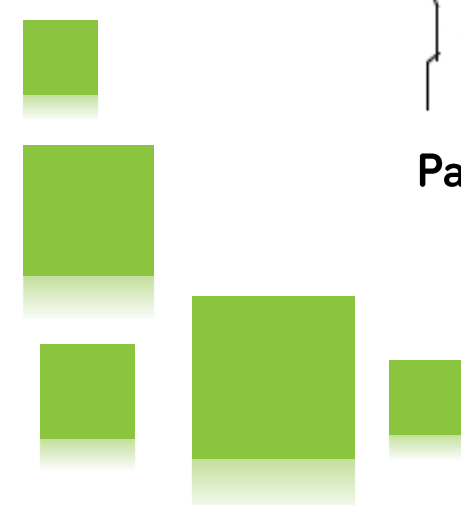
Optical & Mechanical



Paddle wheel (4 pockets)

installed at point of discharge of the clean-grain elev.

Input data { V_{pocket} (L)
 Number of discharges/s
 ρ_{grain} } \longrightarrow to convert L/s \rightarrow kg/s



Swath width

Most Y monitors allow the operator to indicate (Y monitor's touch-screen) whether the combine harvester is operating at a 100% w_c or less ('eye' estimation in the latter case..)

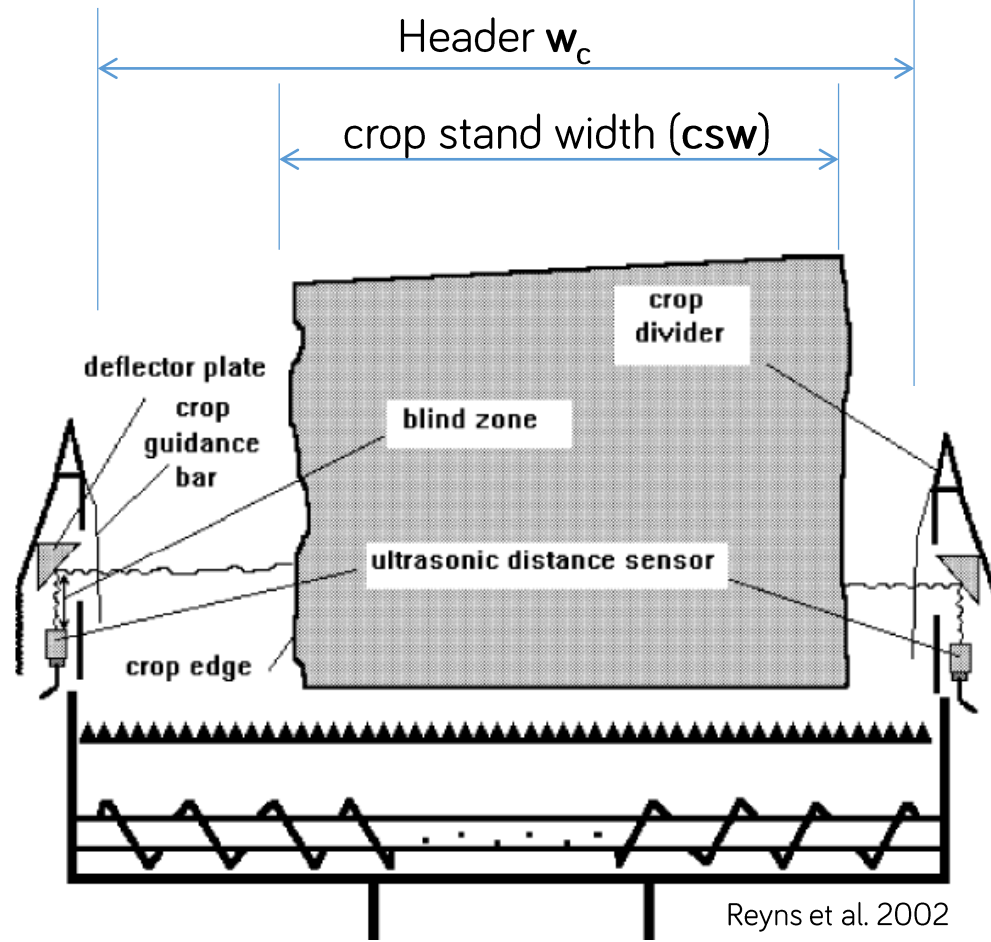


Technical advance: Measurement of w_c by aid of US sensors

easier for corn: count the number of rows instead of estimating a % of the header cut width w_c

depicted case:

$$CSW < w_c$$



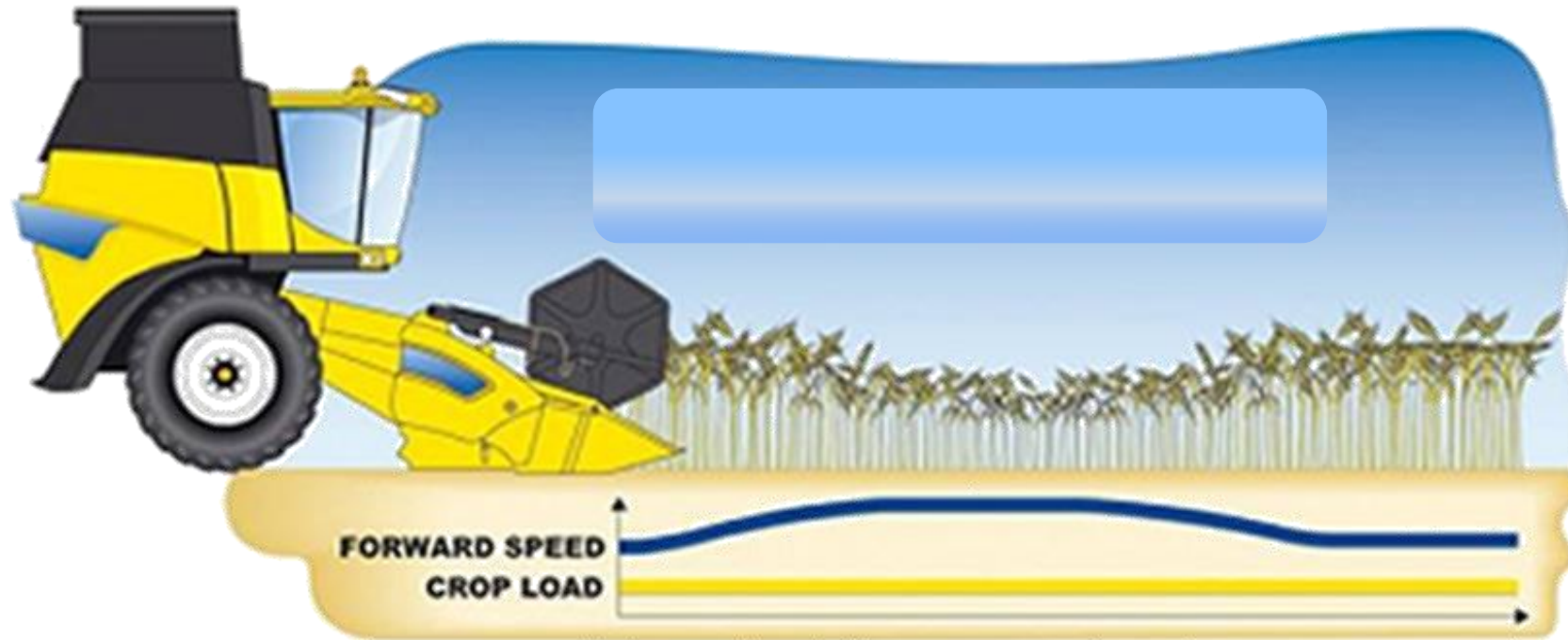
(If the system is not informed that the trip is not a full-width one, Y will be underestimated)

Combine harvester Forward ground Speed

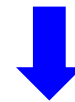


'Conflict of interest'

Constant crop load: Combine's automatic control which **adjust fwd. ground v** to maintain a constant machine load (grain intake rate)



For the sake of yield map accuracy, constant ground speed is recommended



If main interest is obtaining a yield map, *constant crop load* function should be disengaged



Yield sensor calibration (1/2)

◆ Due: Often

- Conventional, manual (batch calibration)

- time-consuming

- calibration process:

- 1st: Harvest a small (e.g. 1500 kg) load of grain

- 2nd: Drive to the *Weighbridge* to measure the *truck scale* weight

Calibration factor

$$C = C_{\text{std.}} \cdot \frac{(m \cdot g)_{\text{monitor}}}{(m \cdot g)_{\text{truck scale}}}$$

$C_{\text{std.}}$ = default calibration factor for the grain type considered

Typ.: 2-6 loads/calibration

(points in the calibration curve)

- Continuous, automated

(e.g., JD's *ActiveYield*)

- Provides **continuous** calibration of the mass flow sensor through **load cells installed in the grain tank**

- Load Cells in the grain tank estimate the change in **weight** of grain, as the grain tank fills

Yield sensor calibration (2/2)



grain cart
more in USA than
in Eur./Spain

What is an ActiveYield Load?

It is not a full **grain tank** and it is not a full truck/**grain cart** load.

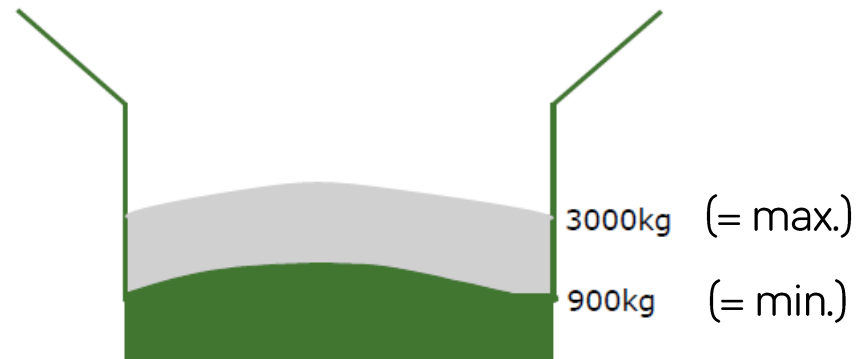
The system starts taking data when the load cells indicate that grain is accumulating in the grain tank @900kg.(2000lb.) (min.)

ActiveYield **stops** accepting measurements when the load cells indicate the grain weight @ 3000kg.(6600lb.) (max.)

Load will be saved as long as:

- Harvested crop is uniform to support constant flow during load collection
- Field terrain (roll and pitch) are within $\pm 4^\circ$
- No interruptions with grain flow during **load collection** (stopping-starting, unloading, grain pile shift, disengaging separator).

↓
commutes
between CH &
field edge
where the
semi-trailer
truck waits...



Protein sensor

“On-the-go combine **protein sensors** increase wheat margins”



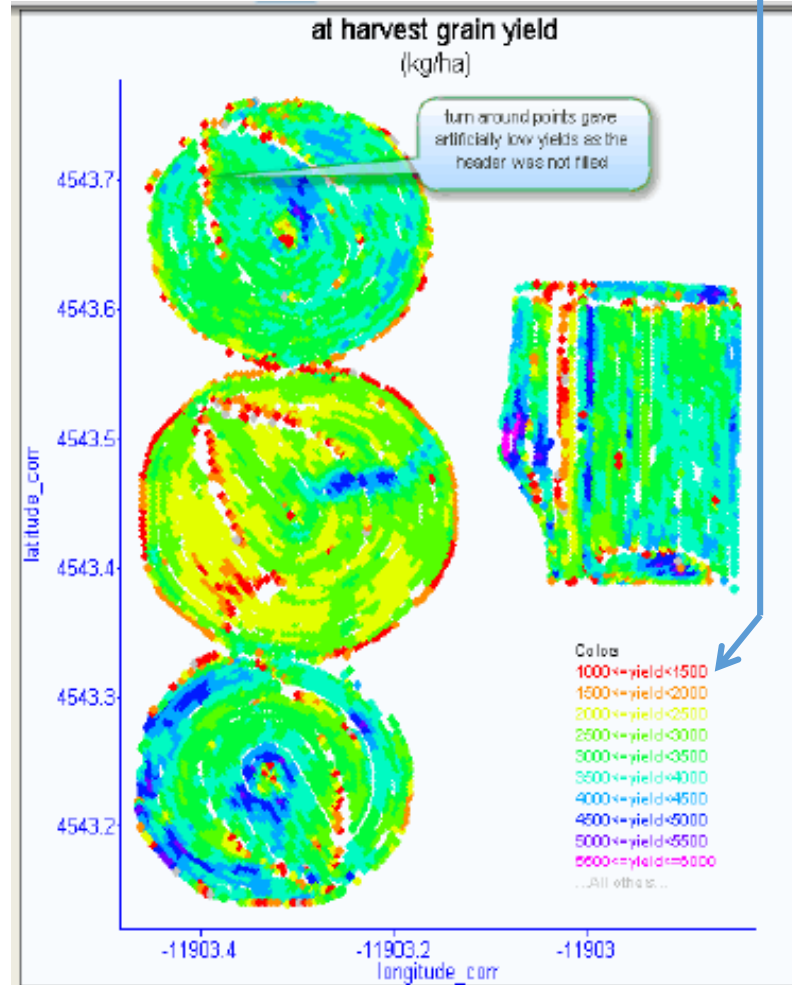
Protein sensor mounted on the clean grain elevator



Yield & Protein Maps (1/2)

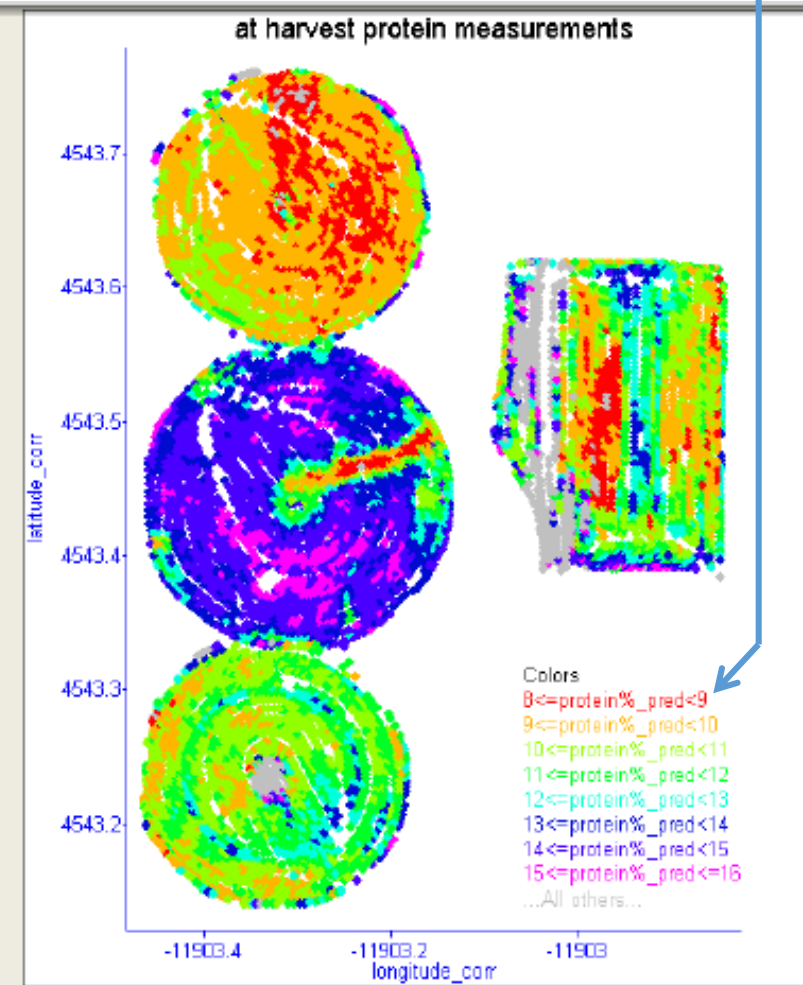


Red: yield between (btw.) 1000 and 1500 kg/ha



Red: % protein btw. 8 and 9

Pink: % protein btw. 15 and 16



Yield & Protein Maps (2/2)



Spot of ↑ kg/ha
and ↓ % protein

